

Adaptive Mesh Refinement in Chapel Part I: Hard problems made easy

Jonathan Claridge University of Washington March 2, 2011









Overview of two talks

- This talk:
 - Several AMR challenges that Chapel makes easy
- Next talk:
 - A difficult part of AMR that Chapel sets us up to solve







What is adaptive mesh refinement (AMR)?

 Method for solving partial differential equations (PDEs) in which resolution is adaptively increased near "interesting" features

Movie omitted to reduce file size









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Language	Parallelism	SLOC ¹	Tokens	Relative size (tokens)
C++ (D≤6) ³	Dist. mem.	40200	261427	100%
Fortran (2D+3D) ²	Serial	16562	151992	58%
2D		8297	71639	27%
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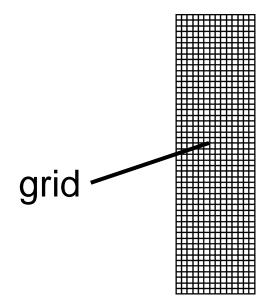
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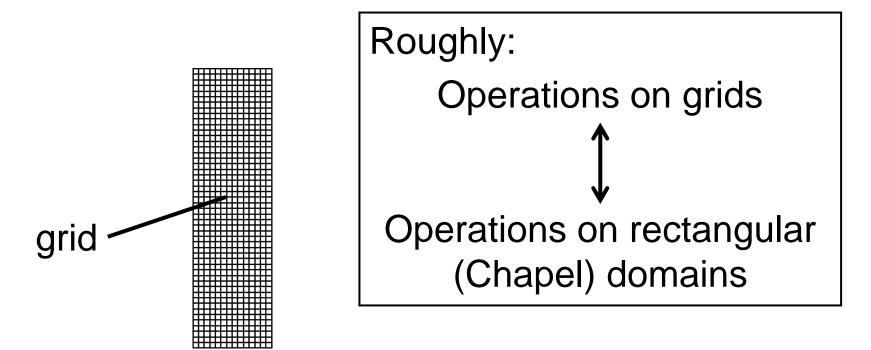








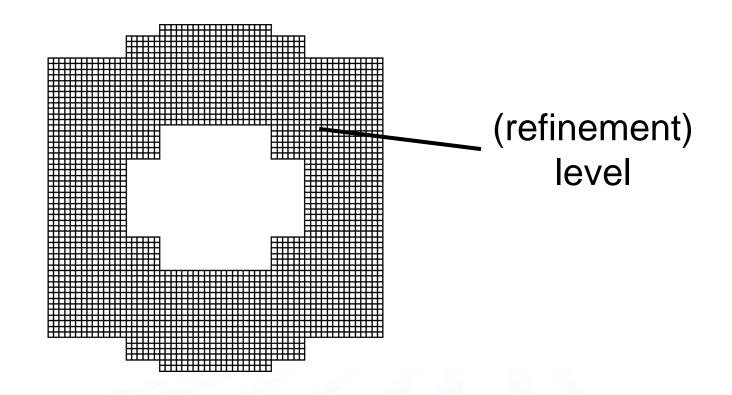








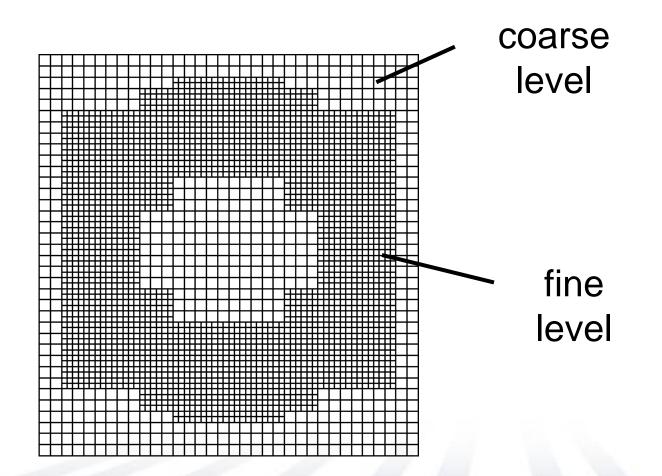










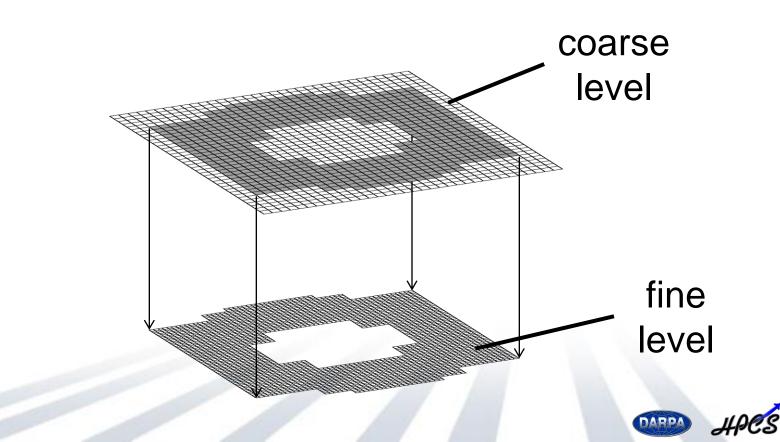


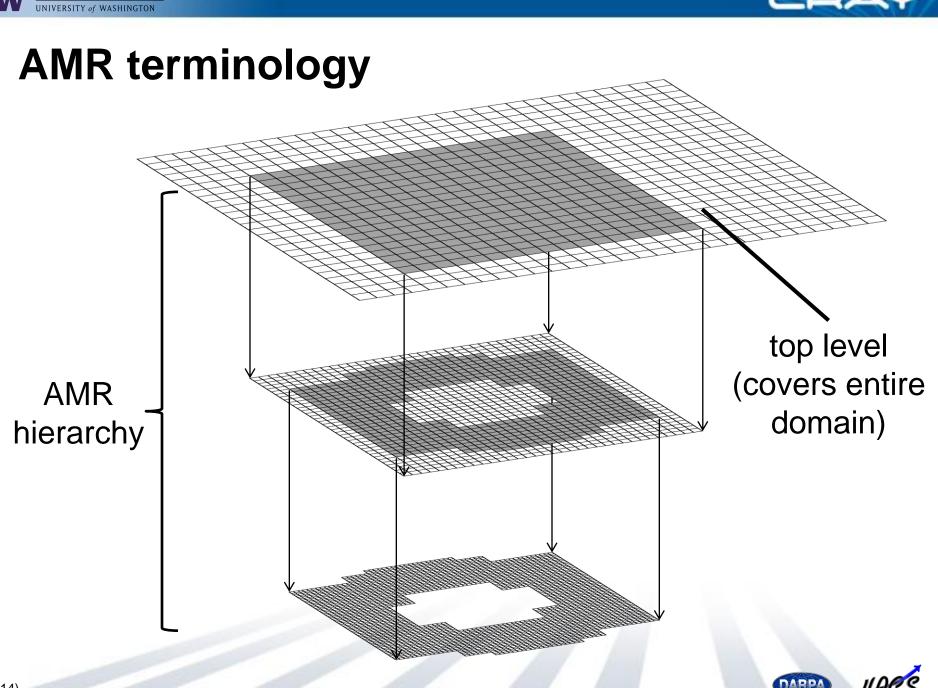












APPLIED MATHEMATICS





Conventional indexing – number grid cells sequentially

3	×	×	×	×
2	×	×	×	×
1	×	×	×	×
	1	2	3	4









Conventional indexing – number grid cells sequentially

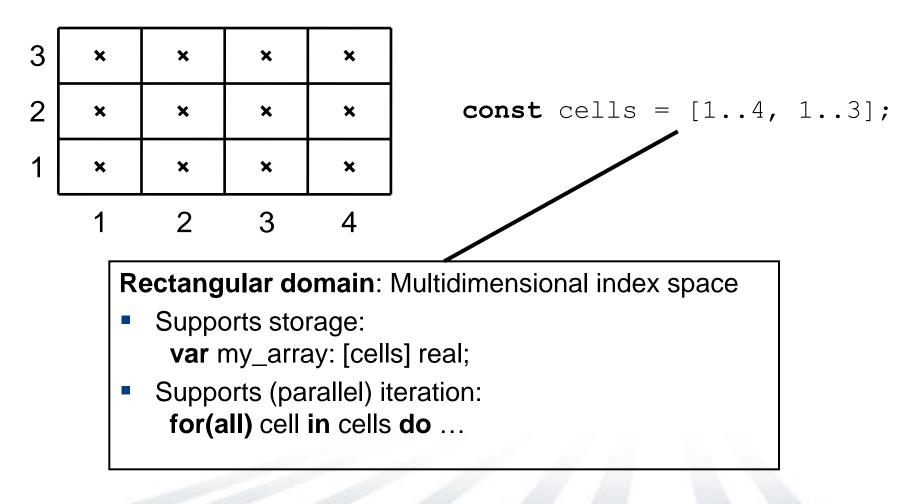
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 - Usual approach: Interface has the same index as the cell above it







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 $(2,3)$ $(2,3)$ $(2,3)$







Conventional indexing – number grid cells sequentially

3	×	×	×	×
2	×	×	×	×
1	×	×	×	×
	1	2	3	4

const cells = [1..4, 1..3];

- Problem with conventional indexing: How are the interfaces indexed?
 - Usual approach: Interface has the same index as the cell above it

$$(2,3)$$
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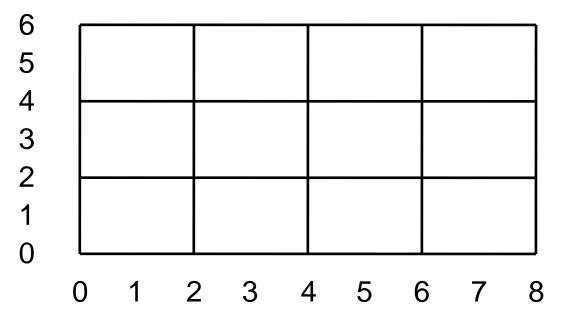
Many objects will have the same indices







Modified approach – denser index space

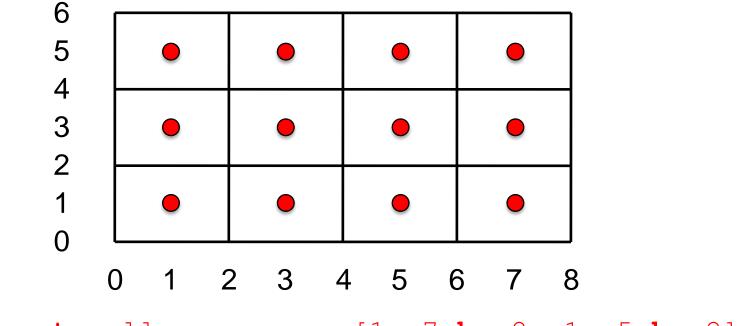








Modified approach – denser index space



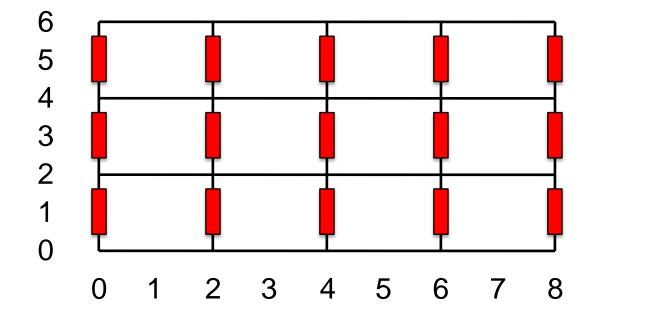
const cells = [1..7 by 2, 1..5 by 2];







Modified approach – denser index space



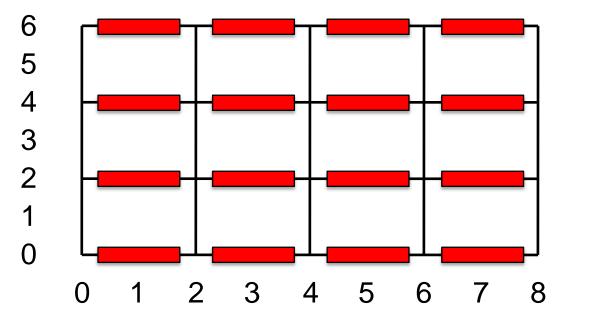
const cells = [1..7 by 2, 1..5 by 2]; const x_interfaces = [0..8 by 2, 1..5 by 2];







Modified approach – denser index space



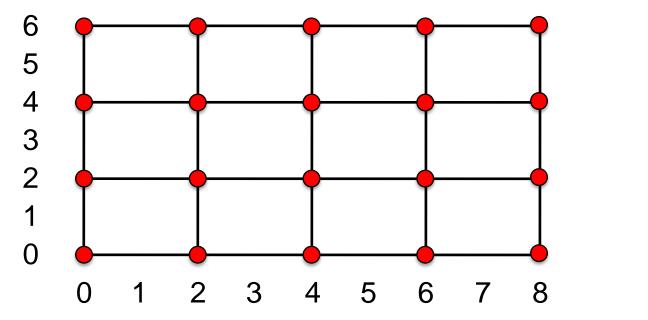
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Modified approach – denser index space



const cells = [1..7 by 2, 1..5 by 2]; const x_interfaces = [0..8 by 2, 1..5 by 2]; const y_interfaces = [1..7 by 2, 0..6 by 2]; const vertices = [0..8 by 2, 0..6 by 2];







Modified approach – denser index space



Strided domains

- Array and iteration syntax are unchanged
- Chapel helps describe the mathematical problem much more robustly



- **const** cells = [1..7 by 2, 1..5 by 2];
- const x_interfaces = [0..8 by 2, 1..5 by 2];
- const y_interfaces = [1..7 by 2, 0..6 by 2];
- **const** vertices = [0..8 **by** 2, 0..6 **by** 2];

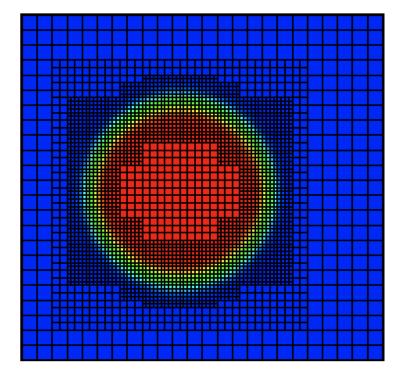


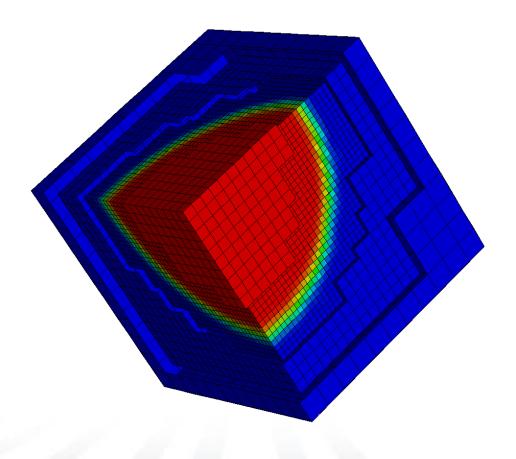
DARPA





Use the same code to produce results in 2D, 3D, 6D, 17D...











 Goal: Use rank-independent domain construction to define a grid of arbitrary spatial dimension









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- Begin by setting

```
config param dimension: int;
```

Specifies a compile-time constant (**param**) that may be specified at the command line (**config**).



(32)





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- Begin by setting config param dimension: int;
 Specifies a compile-time constant (param) that may be specified at the command line (config).
- A grid is defined by:

```
const x_low, x_high: dimension*real; Coordinate bounds
const n_cells: dimension*int; Coordinate bounds
const ghost_layer_width: int; Width of ghost cell layer
const i_low: dimension*int; Lower index bound
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```

Types dimension*real and dimension*int are tuples, a native type.







cells(d);

Grids: Dimension independence

Domain of interior cells:

for d in

subrange

var subranges: dimension*range(stridable=true);

Temporary variable to store sub-ranges of the domain as they are defined

var cells: domain(dimension, stridable=true);
cells = subranges;







Domain of interior cells:

var subranges: dimension*range(stridable=true);

```
for d in 1..dimension do
```

```
subranges(d) = (i_low(d)+1 \dots by 2) #n_cells(d);
```

var cel cells = Assign subranges in each dimension; this is the only place that the dimensions are unrolled

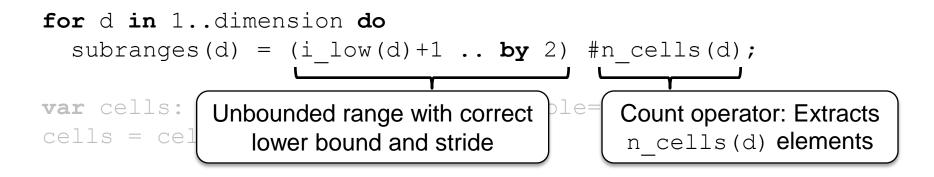






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Define the domain cells







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for d in 1..dimension do
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var cells: domain(dimension, stridable=true);
cells = subranges;
```

Domain of all cells, including ghost cells (spatial variables will be defined here):

```
var extended_cells = cells.expand(2*ghost_layer_width);
```

Cell centers are two indices apart







Domain of interior cells:

var subranges: dimension*range(stridable=true);

```
for d in 1..dimension do
   subranges(d) = (i_low(d)+1 .. by 2) #n_cells(d);
var cells: domain(dimension, stridable=true);
cells = subranges;
```

Domain of all cells, including ghost cells (spatial variables will be defined here):

Array declarations are automatically rank-independent:
 var spatial variable: [extended cells] real;

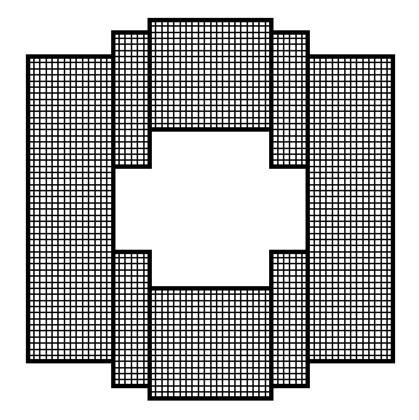






Levels

Essentially a union of grids





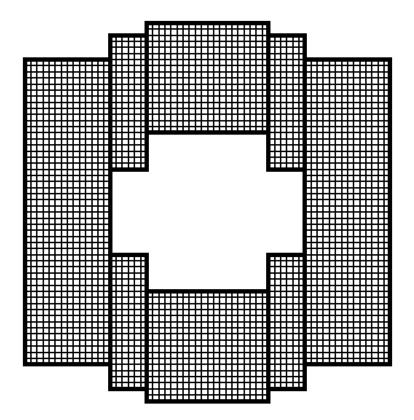




Levels

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var grids: domain(Grid);









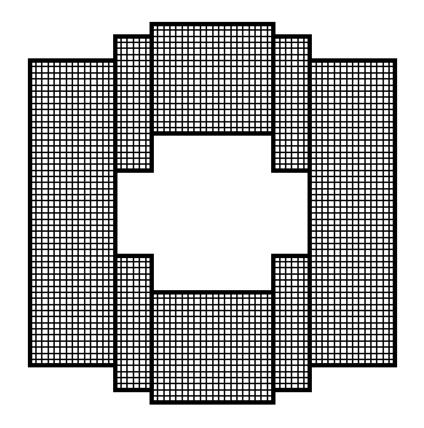
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Essentially a union of grids

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var grids: domain(Grid);
```



- List of indices of any type
- Array and iteration syntax are unchanged

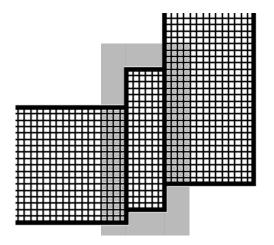








 A grid's layer of ghost cells will, in general, overlap some of its siblings. Data will be copied into these overlapped ghost cells prior to mathematical operations.

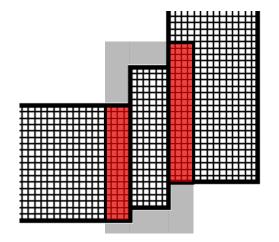








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- Calculating the overlaps between siblings:







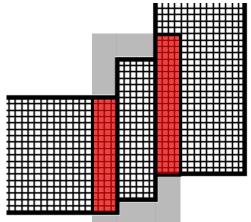


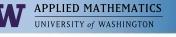


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- Calculating the overlaps between siblings:

```
var neighbors: domain (Grid);
var over
Declare associative domain to store
neighbors; initializes to empty.
for sibl
var overlap = extended_cells( sibling.cells );

if overlap.numIndices > 0 && sibling != this {
    neighbors.add(sibling);
    overlaps(sibling) = overlap;
  }
}
```







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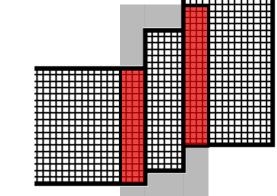
if overl

neigh



Levels: Sibling overlaps

- A grid's layer of ghost cells will, in general, overlap some of its siblings. Data will be copied into these overlapped ghost cells prior to mathematical operations.
- Calculating the **overlaps** between siblings:



- var neighbors: domain(Grid);
 - var overlaps: [neighbors] domain(dimension, stridable=true);

for sibling in parent level.grids var over

Loop over all grids on the same level, checking for neighbors.

overlaps(sibling) = overlap;

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var neighbors: domain(Grid);
var overlaps: [neighbors] domain(dimension,stridable=true);
```

```
for sibling in parent_level.grids {
    var overlap = extended_cells( sibling.cells );
```

Computes intersection of the domains <code>extended_cells</code> and <code>sibling.cells</code>.

Take a moment to appreciate what this calculation would look like without domains!







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```
if overlap.numIndices > 0 && sibling != this {
    neighbors.add(sibling);
    overlaps(sibling) = overlap;
}

If overlap is nonempty, and
    sibling is distinct from this
    grid, then update stored data.
```







- Three major challenges
 - Data coarsening
 - Data refinement
 - Regridding

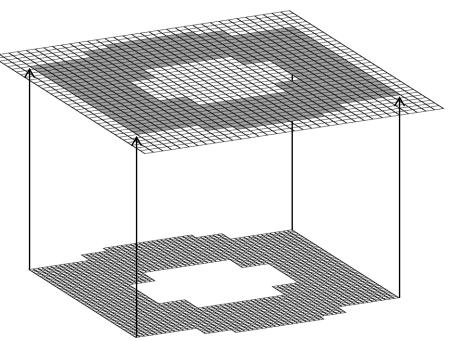








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 - Coarsening
 - Data transfer occurs on intersection of coarse grid and fine grid

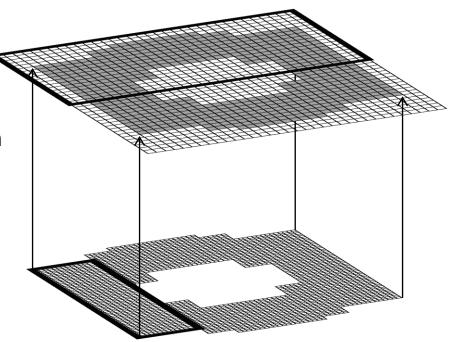








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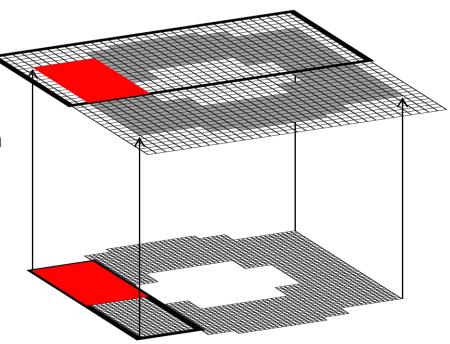








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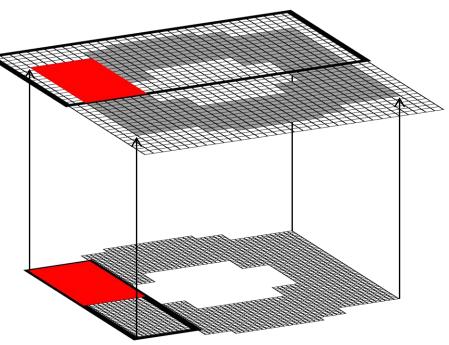








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 - Region is rectangular transfer is relatively easy

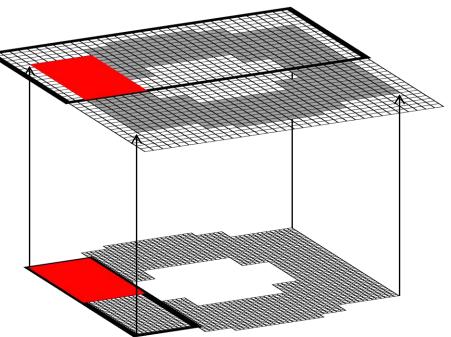








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- Refinement and regridding
 - Involve unions and subtractions of rectangles
 - Much harder; subject of next talk









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- Rectangular domains and associative domains are both very important
- Haven't discussed objects for data storage, but Chapel's link between domains and arrays makes them easy to define and use
- A recap of code size, now that you've seen some of the interesting parts:

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Thank You.

This material is based upon work supported by the Defense Advanced Research Projects Agency under its Agreement No. HR0011-07-9-0001. Any opinions, findings and conclusions or recommendations expressed in this material are those of the author(s) and do not necessarily reflect the views of the Defense Advanced Research Projects Agency.

Questions?

