Runtime Optimizations for Irregular Applications in Chapel

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Outline

- Motivation and background
 - Irregular applications
 - Inspector-executor technique
- High-level design of inspector-executor
- Performance evaluation
 - NAS-CG, moldyn, PageRank
- Future work

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1.) Motivation and Background

- Memory wall: processor speeds outpace rate at which data can be fetched from memory
 - leads to data starvation of compute resources
- Even worse for irregular applications
 - sparse, unstructured memory access patterns found in graph analytics
 - lack of spatial/temporal locality leads to fine-grained, remote communication
 - memory access patterns not known at compile time
 - requires **runtime-based** optimizations

1.) Motivation and Background (cont.)

- Inspector-executor technique
 - inspector → analyze a kernel of interest (memory access pattern, loop iteration dependencies, etc.)
 - executor → generate an optimized version of the kernel that utilizes the inspector's analysis (loop reordering, data reordering, etc.)

1.) Motivation and Background (cont.)

- Inspector-executor technique
 - inspector → analyze a kernel of interest (memory access pattern, loop iteration dependencies, etc.)
 - executor → generate an optimized version of the kernel that utilizes the inspector's analysis (loop reordering, data reordering, etc.)
- To achieve performance gains, the overhead of the inspector needs to be amortized over multiple executions of the kernel
 - kernel does not change between iterations
 - examples: conjugate gradient, molecular dynamics simulations, PageRank
- The inspector and executor can be **generated by the compiler**
 - in this preliminary work, we **hand-code** the inspector and executor to demonstrate the potential of the optimization

Outline

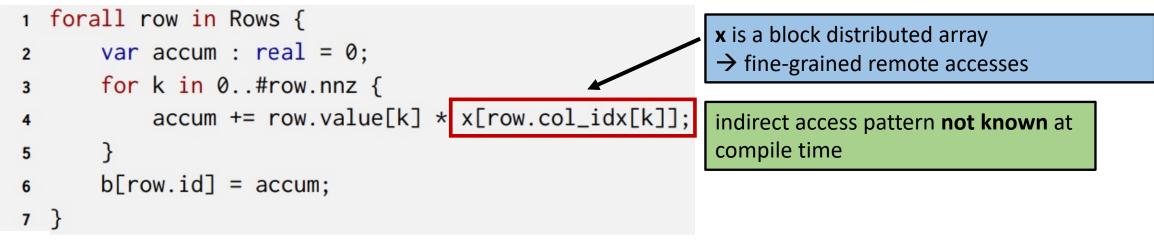
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```
1 forall row in Rows {
2     var accum : real = 0;
3     for k in 0..#row.nnz {
4         accum += row.value[k] * x[row.col_idx[k]];
5     }
6     b[row.id] = accum;
7 }
```

Sparse Matrix-Vector Multiply (SpMV) kernel

1	<pre>forall row in Rows {</pre>	Rows is a block distributed array
2	var accum : real = 0;	
3	<pre>for k in 0#row.nnz {</pre>	A given row is operated on the locale where
4	<pre>accum += row.value[k] * x[row.col_idx[k]];</pre>	it is stored
5	}	
6	<pre>b[row.id] = accum;</pre>	
7	}	

Sparse Matrix-Vector Multiply (SpMV) kernel



Sparse Matrix-Vector Multiply (SpMV) kernel



Sparse Matrix-Vector Multiply (SpMV) kernel

GOAL: Eliminate all remote accesses to **x** during the kernel

APPROACH:

- inspect which col_idx[k] result in remote accesses to x for a given locale
- **replicate** the remote elements on that locale and access those copies instead

→ Construct a mapping from **col_idx[k]** to **x[col_idx[k]]** for remote accesses

- Replicating remote elements: associative arrays
 - Keys: col_idx[k] values (i.e., indices)
 - Values: x[col_idx[k]] elements (i.e., remote values)

<pre>1 record SparseBuffer {</pre>
<pre>2 type elem_type;</pre>
3 var spD : domain (int);
<pre>4 var arr : [spD] elem_type;</pre>
<pre>5 var start_idx, end_idx, num_elems : int;</pre>
<pre>6 var D : domain(1) = {0#num_elems};</pre>
<pre>var indices : [D] int; // sorted indices</pre>
8 }
Ī

Each locale stores a **SparseBuffer** record to keep track of the remote elements it will need

spD is the associative domain, **arr** is the array declared over the associative domain

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 - Keys: col_idx[k] values (i.e., indices)
 - Values: x[col_idx[k]] elements (i.e., remote values)

• Pros

- clean way to store **sparse** indices
- faster than Chapel's sparse domains/arrays
- automatically ignores duplicates
- can directly use the original col_idx[k] indices as look-ups

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- can directly use the original col_idx[k] indices as look-ups

• Cons

- **slower** access time vs. default arrays (~2-3x)
- more memory usage vs. default arrays (~ 10%)

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spD is the associative domain, **arr** is the array declared over the associative domain

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1 forall row in Rows {
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4         accum += row.value[k] * x[row.col_idx[k]];
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```

original kernel

```
1 forall row in Rows {
       const start = localeBuffers[here.id].start_idx;
2
       const end = localeBuffers[here.id].end_idx;
 3
       ref spD = localeBuffers[here.id].spD;
 4
      for k in 0..#row.nnz {
 5
           const idx = row.col_idx[k];
6
           if idx < start || idx > end {
7
               spD += idx;
8
           }
9
       }
10
11 }
12 sort_indices(localeBuffers);
```

inspector

•

```
1 forall row in Rows {
2     var accum : real = 0;
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original kernel

1	for	rall row in Rows {
2		<pre>const start = localeBuffers[here.id].start_idx;</pre>
3		<pre>const end = localeBuffers[here.id].end_idx;</pre>
4		<pre>ref spD = localeBuffers[here.id].spD;</pre>
5		<pre>for k in 0#row.nnz {</pre>
6		<pre>const idx = row.col_idx[k];</pre>
7		<pre>if idx < start idx > end {</pre>
8		<pre>spD += idx;</pre>
9		}
10		}
11	}	
12	sor	rt_indices(localeBuffers);

- localeBuffers: stores each locale's SparseBuffer
- **start/end**: bounds on the locale's local partition of **x**
- spD: a locale's associative domain

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       const start = localeBuffers[here.id].start_idx;
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       ref spD = localeBuffers[here.id].spD;
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       for k in 0..#row.nnz {
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           const idx = row.col_idx[k];
6
           if idx < start || idx > end {
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               spD += idx;
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10
11 }
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```

Bounds check for remote accesses

- assumes block distribution
- could use .contains() on the local subdomain but we observed significant performance loss
- **future work:** more general, but efficient, approach?

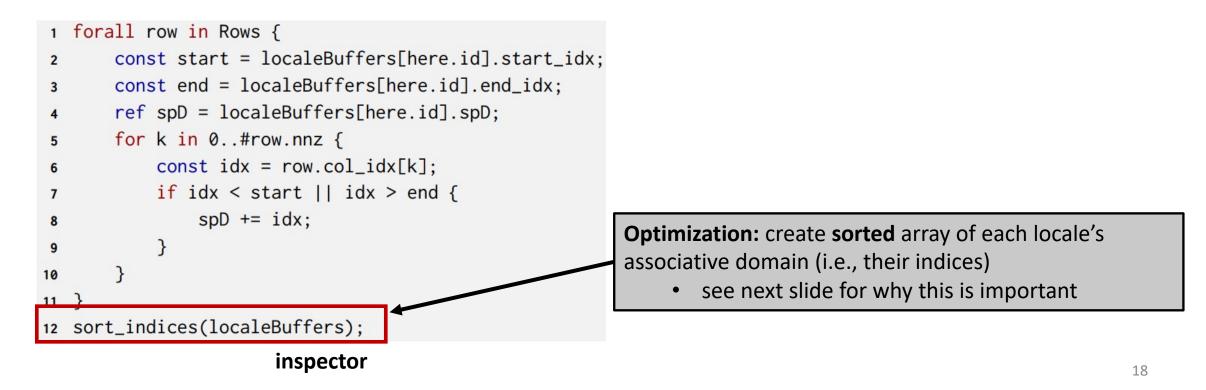
Does not perform actual remote communication

spD is modified by multiple tasks **concurrently**

- forall loop performs both shared- and distributed-memory parallelism → multiple tasks spawned on each locale
- by default, associative domains provide parallel safety for this operation

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```

original kernel

```
1 forall buff in localeBuffers {
       forall idx in buff.indices {
2
           buff.arr[idx] = x[idx];
 3
       }
5 }
6 forall row in Rows {
       const start = localeBuffers[here.id].start_idx;
7
       const end = localeBuffers[here.id].end_idx;
8
       ref arr = localeBuffers[here.id].arr;
9
       var accum : real = 0;
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       for k in 0..#row.nnz {
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           const idx = row.col_idx[k];
12
           if idx < start || idx > end {
13
               accum += row.value[k] * arr[idx];
14
           }
15
           else {
16
               accum += row.value[k] * x[idx];
17
           }
18
       }
19
       b[row.id] = accum;
20
21 }
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executor

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1 forall row in Rows {
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original kernel

Update/gather the original values from x to each locale's replicated copy
→ values most likely changed outside of the kernel

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1 forall buff in localeBuffers {
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original kernel

Update/gather the original values from **x** to each locale's replicated copy

ightarrow values most likely changed outside of the kernel

All updates are **remote reads**. But since each remote element is **stored only once**, we do a single remote read and get "unlimited" local accesses during the kernel

 \rightarrow this is the key to our approach achieving performance gains

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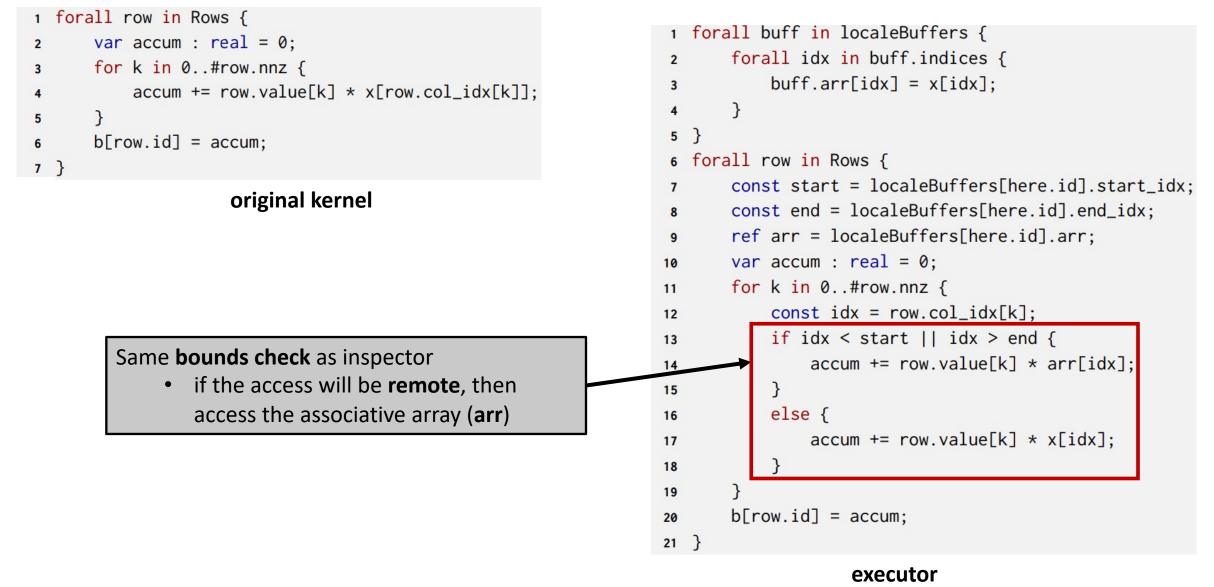
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.indices is a sorted array of the associative array's keys

 associative array indices are unsorted, so directly iterating over them leads to poor locality for Chapel's remote cache

→ observed as much as a 22x speed-up vs. not sorting

```
1 forall buff in localeBuffers {
       forall idx in buff.indices {
2
           buff.arr[idx] = x[idx];
6 forall row in Rows {
       const start = localeBuffers[here.id].start_idx;
       const end = localeBuffers[here.id].end_idx;
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       ref arr = localeBuffers[here.id].arr;
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- Motivation and background
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- Performance evaluation
 - NAS-CG, moldyn, **PageRank** \rightarrow see our paper for moldyn and NAS-CG results
- Future work

3.) Performance Evaluation: Setup

- System:
 - 16 node FDR Infiniband Cluster
 - Each node →512GB DDR4, 2x Intel Xeon E5-2650v3 (20 cores total)
 - Hyperthreading enabled
- Chapel:
 - 1.24.1, LLVM 11.0.1
 - --fast and --cache-remote
 - GASNet over Infiniband
- Results:
 - average over multiple trials (coefficient of variation does not exceed 0.07)
- Comparisons:
 - **Baseline** \rightarrow no inspector-executor optimization
 - **Replicate-all** \rightarrow no inspector performed, just give each locale a full copy of the array
- Will refer to inspector-executor as I/E

3.) Performance Evaluation: PageRank

- Evaluate two real web-graphs and two Graph500 graphs (https://graph500.org/)
- Execute **until convergence**: tolerance of **1e-10**, damping factor of **0.85**
- Baseline only runs 1 iteration of Graph500 graphs
 - for 2 locales, estimated to require 20 days for all iterations on g500_scale-28
 - baseline results are extrapolated from single iteration runtimes

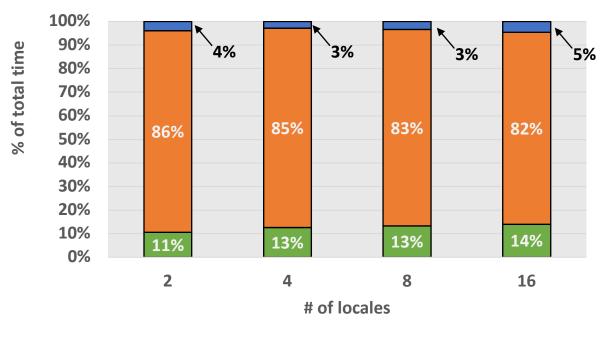
Name	Vertices	Edges	Density (%)	Memory	Iterations
arabic-2005	23M	630M	1.2e-4	26 GB	94
sk-2005	51M	1.9B	7.5e-5	63 GB	82
g500_scale-26	67M	2.1B	4.7e-5	79 GB	29
g500_scale-28	268M	8.5B	1.2e-5	318 GB	20

Table 3: Data Sets for PageRank

PageRank: arabic-2005

- Inspector runtime overhead:
 - **geomean** overhead of 5% relative to the total execution time
- Low overhead due to many iterations, allowing for overhead to be amortized

g500_scale-28



■ INSPECTOR ■ UPDATE ■ KERNEL

- I/E memory usage:
 - geomean increase in memory over the baseline of 80%
 - high memory usage is due to the large Graph500 graphs
 - memory usage increase for real-world graphs is **42%**

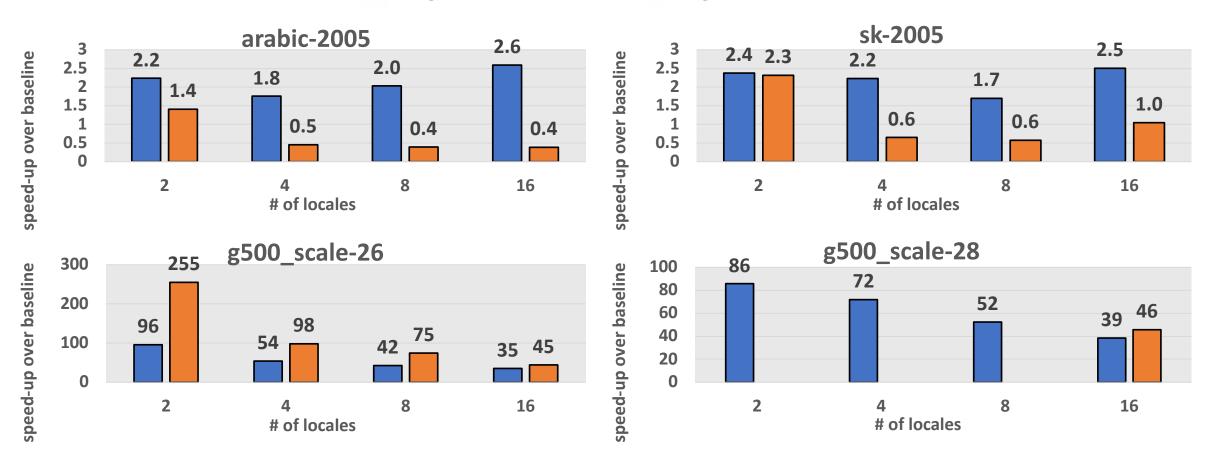
- I/E memory usage:
 - geomean increase in memory over the baseline of 80%
 - high memory usage is due to the large Graph500 graphs
 - memory usage increase for real-world graphs is **42%**
- Replicate-all memory usage:
 - geomean increase in memory over baseline of 606%
 - cannot run g500_scale-28 on 2, 4, or 8 locales →out of memory
 - real-world graph memory usage increase is 565%

Key Point: I/E replicates less data than replicate-all

- I/E only replicates what will be accessed remotely
- replicate-all replicates **EVERYTHING**

PageRank Runtime Speed-ups

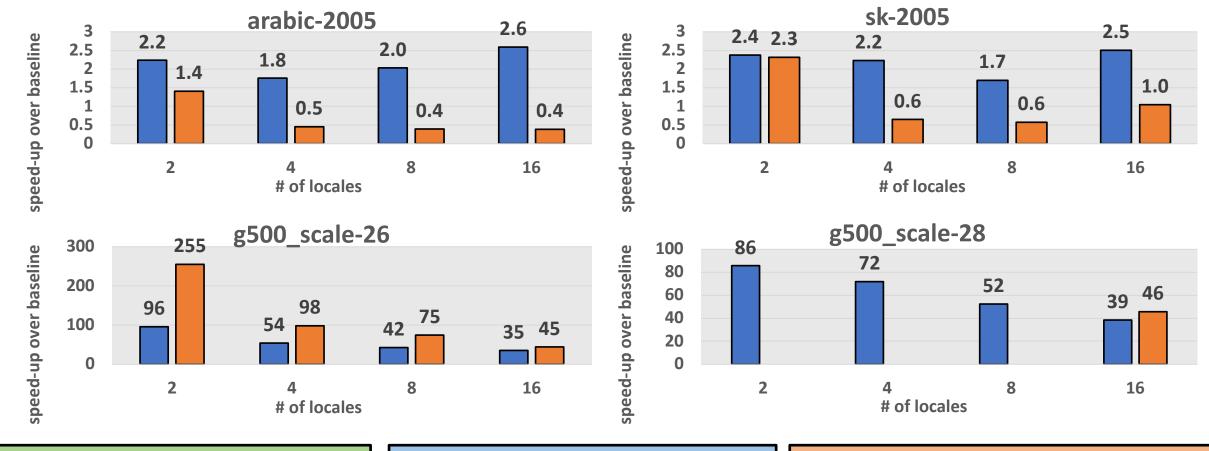
Inspector-Executor Replicate-All



- I/E: geomean speed-up of **11x**
- Replicate-all: geomean speed-up of **5x**

PageRank Runtime Speed-ups

Inspector-Executor Replicate-All



I/E exploits data reuse

- single remote get per remote element gives us "unlimited" local accesses
- I/E replicates less data
- spends less time in the gather/update phase than replicate-all

I/E slower on Graph500 graphs vs replicate-all

- I/E needs to replicate virtually all the elements
- Performance now bounded by access costs to associative arrays vs. default arrays

- Noteworthy comparisons
 - For two locales:
 - baseline estimated to require **20 days** to run all iterations on g500_scale-28
 - I/E does it in 6 hours
 - For 16 locales:
 - baseline estimated to require **41 hours**
 - I/E does it in 1 hour

3.) Performance Summary

- Note far right column
 - relatively few iterations required until I/E is on par, or faster, than baseline

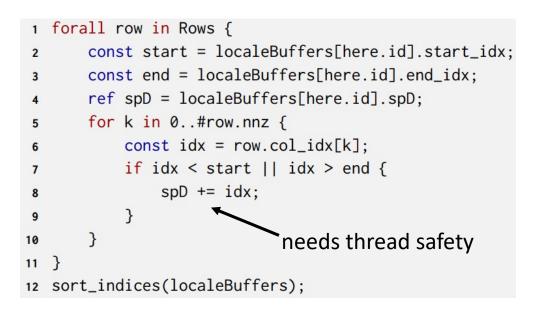
Application	Average Memory Overhead	Average Inspector Overhead	Average Runtime Speed-up	Max # of Iterations to Break Even with Baseline
NAS-CG	6%	4%	27x	2
moldyn	4%	24%	8x	1
PageRank	80%	5%	11x	4

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4.) Future Work

- Optimizing the optimization:
 - transform forall to coforall for inspector to speed-up associative domain operation
 - forall loop over distributed array will spawn multiple tasks per locale
 - need **parallel-safety** for associative domain (parSafe=true)
 - Use a **coforall** instead, allowing us to set parSafe=false
 - Reduces parallelism but still gives us net performance gains (as much as **6x faster**)
 - Generally, this transformation can be done, but not always true



1	coforall loc in Locales do on loc {
2	<pre>const rowIndices = rows.localSubdomain();</pre>
3	<pre>const start = rowIndices.low;</pre>
4	<pre>const end = rowIndices.high;</pre>
5	<pre>ref spD = localeBuffers[loc.id].spD;</pre>
6	<pre>for i in rowIndices {</pre>
7	<pre>ref row = Rows[i];</pre>
8	<pre>for k in 0#row.nnz {</pre>
9	<pre>const idx = row.col_idx[k];</pre>
10	<pre>if idx < start idx > end {</pre>
11	<pre>spD += idx;</pre>
12	}
13	does not need
14	}
15	<pre>} thread safety</pre>
16	<pre>sort_indices(localeBuffers);</pre>

4.) Future Work (cont.)

- Optimizing the optimization:
 - use **aggregation** for the update/gathers before the kernel
 - use **default arrays** instead of associative arrays
 - more efficient memory accesses
 - requires building a new index mapping from **indirection array** to indices in the default array
 - gets much uglier than the associative array approach, so there's a tradeoff between performance and what the compiler could automatically generate

4.) Future Work (cont.)

- Optimizing the optimization:
 - use **aggregation** for the update/gathers before the kernel
 - use **default arrays** instead of associative arrays
 - more efficient memory accesses
 - requires building a new index mapping from **indirection array** to indices in the default array
 - gets much uglier than the associative array approach, so there's a tradeoff between performance and what the compiler could automatically generate
- Compiler automation:
 - user driven (pragmas) or have the compiler try to find suitable kernels?
- More applications please!
 - not ideal for the optimization developer to write the test cases
 - if you have irregular applications that could benefit from runtime optimizations (not just inspector-executor), contact us! tbrolin@cs.umd.edu

Conclusions

- Inspector-executor shows promise for irregular applications in Chapel
- Speed-ups as high as **224x**
- Take application runtimes from days to hours
- Does not rely on low-level details to be exposed in the source code
 - our goal with the baseline implementations was to write them in the most natural way, sticking to the "on-paper" description of the algorithms

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